The Power of Polynomials

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Motivation: Polynomials Everywhere, I

Are the loops parallel? Are there loop-carried dependences?

Can be solved by *delinearization*, or by the SMT solver Z3, or by ISL using Bernstein polynomials. Other approaches?

Polynomials Everywhere: Scheduling

Find a schedule for:

```
s = 0.;
for(i=1; i<N; i++)
  for(j=0; j<i; j++)
  s += a[i][j];</pre>
```

Since the program runs in time $O(N^2)$ whatever the number of processors, it has no affine schedule. It has a two-dimensional schedule, which is equivalent to a quadratic schedule.

Can one find the quadratic schedule directly?

Polynomials Everywhere: Transitive Closure

What is the *exact* transive closure of:

$$(x' = x + y, y' = y, i' = i + 1)$$
?

Answer:

$$(x' - i'.y' = x - i.y, y' = y, i' \ge i).$$

a polynomial relation.

The Basic Problem

Given: a set K and a function f, is f positive in K:

$$\forall x \in K : f(x) > 0?$$

Extension: f is a *template* depending on a vector of parameters μ . Find μ such that:

$$\forall x \in K : f_{\mu}(x) > 0.$$

Farkas lemma is the case where K is a polyhedron $K = \{x \mid Ax + b \ge 0\}$ and f is affine. The solution is:

$$f(x) = \lambda_0 + \lambda \cdot (Ax + b), \lambda \ge 0$$

Notations

A semi-algebraic set (sas):

$$K = \{x \mid p_1(x) \ge 0, \dots, p_n(x) \ge 0\}$$

where x is a set of unknowns x_1, \ldots, x_p and the p_i s are polynomials in x. A polyhedron is an sas such that all the p_i s are of first degree.

Schweighofer products: for each $\vec{e} \in \mathbb{N}^n$:

$$S_{\vec{e}}(x) = p_1^{e_1}(x) \dots p_n^{e_n}(x) = \prod_{i=1}^n p_i^{e_i}(x).$$

Given a finite subset $Z \subset \mathbb{N}^n$ the associated Schweighofer sum is:

$$S_Z(x) = \sum_{\vec{e} \in Z} \lambda_{\vec{e}}.S_{\vec{e}}(x), \ \lambda_{\vec{e}} > 0.$$

Clearly, all Schweighofer sums are positive in K.

Theorems

Theorem (Handelman, 1988)

If K is a compact polyhedron, then a polynomial p is strictly positive in K if and only if it can be represented as a Schweighofer sum for some finite $Z \in \mathbb{N}^n$.

Theorem (Schweighofer, 2002)

If K is the intersection of a compact polyhedron and a semi-algebraic set, then a polynomial p is strictly positive in K if it can be represented as a Schweighofer sum for some finite $Z \in \mathbb{N}^n$.

Notice the similarity between the *conclusion* of the two theorems, and the difference with Farkas lemma: since there is no known bound on the size of Z, it is usually impossible to obtain a negative answer.

Algorithm H

The aim of this algorithm is to collect a set $\mathcal C$ of constraints on the unknowns λ and μ .

- $ightharpoonup C = \emptyset.$
- ▶ Given: a set of Schweighofer products $\{S_{\vec{e}}(x) \mid \vec{e} \in Z \subset \mathbb{N}^n\}$ and a polynomial (template) $p_{\mu}(x)$,
- ▶ Result: A system of constraints on the λ and μ .
- Completely expand the master equation:

$$E = p_{\mu}(x) - \sum_{\vec{e} \in Z} \lambda_{\vec{e}}.S_{\vec{e}}(x).$$

For each monomial $x_1^{f_1} \dots x_p^{f_p}$, collect its coefficient c and add c = 0 to C. c is an affine form in the λ and μ .

Comments

- Algorithm H works equally well in the Handelman or Schweighofer case, provided one use a uniform representation of polynomials, whatever their degree.
- ► The main difficulty is the selection of the products. One may use an oracle(!), or all products of a given degree, or all products of a given number of antecedents.
- The resulting system of constraints may be used in many ways: it may be solved by itself, or may be combined with other constraints before solving.
- ▶ If a solution for the λ and μ is found, this solution can be certified, independently of Handleman or Schweighofer, by straightforward algebraic evaluation.

Dependence Tests

A dependence set D is defined by a system of constraints:

- ▶ The iteration domains of its source and destination,
- A set of subscript equations,
- An order predicate.

Some or all of these constraints may involve polynomials. The problem is to decide whether this set is empty or not.

A possible solution is to prove, using algorithm H, that -1 is a positive combination of Schweighofer products of D! Since -1 can never be positive, it follows that the constraints defining D

cannot all be satisfied at the same time, i.e. that D is empty. Compare to the familiar Fourier-Motzkin algorithm.

An Example

The dependence set:

$$\begin{array}{lll} & \text{for}(i = 0; i < n; i + +) \\ & \text{for}(j = 0; j < n; j + +) \\ & \text{a}[N * i + j] = 0.; \end{array} \quad \begin{array}{lll} 0 \leq i \leq N - 1 & , & 0 \leq i' \leq N - 1 \\ 0 \leq j \leq N - 1 & , & 0 \leq j' \leq N - 1 \\ & Ni + j & = Ni' + j' \\ & i + 1 & \leq i' \end{array}$$

Algorithm H finds the following solution:

$$-1 = (N-i-1)(i'-i-1) + i(i'-i-1) + (i'-i-1) + j' + (N-j-1) + (Ni+j-Ni'-j')$$

Hence, the dependence set is empty.

Scheduling

Notations

- \triangleright R, S, . . . a set of instructions
- D_R the iteration domain of R, usually a polyhedron, sometimes an sas
- ▶ $\Delta_{RS} \subseteq D_R \times D_S$, a dependence set from R to S.

Problem For each statement R find a function $\theta_R: D_R \to \mathbb{Z}$ such that:

$$x \in D_R \Rightarrow \theta_R(x) \ge 0$$

$$\begin{pmatrix} x \\ y \end{pmatrix} \in \Delta_{RS} \Rightarrow \theta_R(x) + 1 \le \theta_S(y)$$

Method

- ▶ For each statement R, build a template schedule θ_R by applying the first part of algorithm H to D_R
- ▶ For each dependence, build a master equation for the *delay* $\theta_S(y) \theta_R(x) 1$ by applying algorithm H to Δ_{RS}
- ▶ Collect the constraints and solve for the λ and μ s using a linear programming tool.

Dependences Scheduling

DEMONSTRATION

Result

```
table((\_node,S) = [[i,j], \{(N >= i+1), (i >= j+1), (i >= 1), \}
          (i \ge 0)]. (nodes) = [S]. (transition.T0) = [S.S.table(i = i', i = i')].
                \{(i' >= i+1)\}] (transition.T1) = [S.S.table(i = i', j = j').\{(i = i')\}
                        (j' >= j+1)],(_transitions) = [T0,T1]
(N * N)*mu 6+N*i*mu 11+N*i*mu 8+N*i*mu 15+N*mu 5+(i * i)*mu 12+
(j * j)*mu_16-j*mu_15-j*mu_16-j*mu_17-j*mu_7-mu_10-mu_5-mu_7
dependence polyhedron \lceil (N \ge i+1), (N \ge i'+1), (i' \ge i+1), (i \ge i+1), (i' \ge 
       (i \ge 1), (i' \ge j'+1), (i' \ge 1), (j \ge 0), (j' \ge 0)]
dependence polyhedron [(N \ge i+1), (N \ge i'+1), (i = i'), (i \ge i+1), (i \ge 1),
       (i' >= i'+1).(i' >= 1),(j' >= j+1),(j >= 0),(j' >= 0)]
table(mu = 0.mu 10 = 1/2.mu 11 = 0.mu 12 = 0.mu 13 = 1/2.mu 14 = 1.mu 15 = 0.
         mu_16 = 0, mu_17 = 0, mu_18 = 0, mu_5 = 0, mu_6 = 0, mu_7 = 0, mu_8 = 0, mu_9 = 0
theta[S] = [1/2*(i*i)+i-1/2*i] == (i) + 1/2 . (i-1)*(i-1) + 1/2 . (i-1)
delay [T0] = 1/2*i+1/2*(i' * i')+i'-1/2*(i * i)-1/2*i'-i-1
===(i')+1/2, (i'-i-1)*(i'-1)+1/2, (i'-i-1)*(i-1)+(i-j-1)+(i'-i-1)
```

Related Work

- ► Early work by B. Pugh et. al. using uninterpreted functions, and by van Engelen et. al. using interval analysis
- Polynomial minimization using a Bernstein expansion, implemented in ISL, can be applied to dependence testing
- Work in progress by A. Maréchal and M. Périn (Verimag) on linearization (i.e. getting rid of polynomials) using Handelman theorem and an oracle to control complexity.

Conclusion and Future Work

- ► The method works well and give interesting results in acceptable time, at least for small problems
- ► Other applications: transitive closure, program termination, (perhaps) invariant construction, ressource allocation, ...
- Complexity, very high, exponential in the degree of Schweighofer products
- ► Can one use an oracle to guess which products are useful?

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THE END - QUESTIONS