

Z-Polyhedra and LBLs in PolyLib

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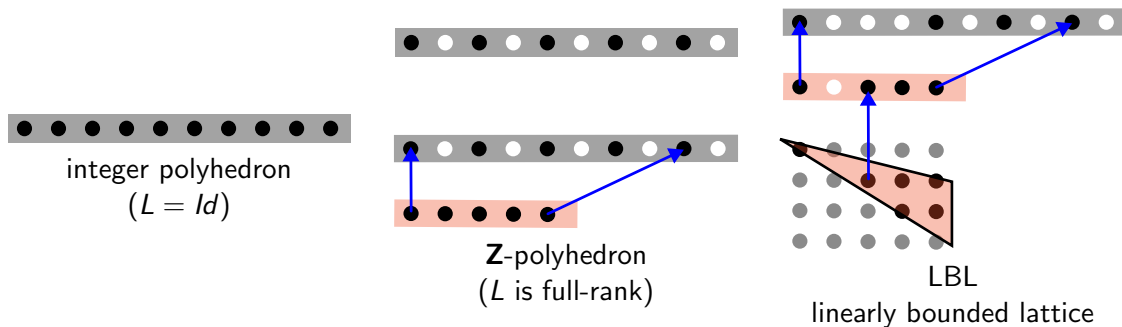
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$$\mathcal{Z} = \left\{ z = Ly + l \mid Cy + c \geq 0, y \in \mathbb{Z}^d \right\}$$

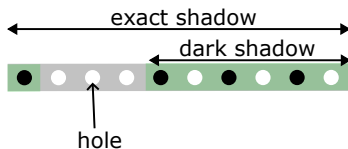


Integer polyhedra \subset **Z**-polyhedra \subset LBLs \subset (unions of **Z**-polyhedra) = (unions of LBLs)

Some History

- Elimination of integer variables in ILP: dark shadow and exact shadow

[Pugh 1991]



Some History

- Elimination of integer variables in ILP: dark shadow and exact shadow [Pugh 1991]
- First implementation of \mathbf{Z} -polyhedra in PolyLib in 2000
[Quinton-Rajopadhye-Risset, 1997] [Nookala-Risset, 2000]

$$\mathcal{Z} = \text{lattice} \cap \text{rational polyhedron}$$

- Representation of \mathbf{Z} -polyhedra and LBLs as the affine image of a full-dimensional integer coordinate polyhedron [Gautam-Rajopadhye, 2007]

$$\mathcal{Z} = \{Lz + l \mid Cz + c \geq 0, z \in \mathbb{Z}^d\}$$

- Same representation, but non-full dimensional integer coordinate polyhedron, at the cost of some more complex algorithms [looss-Rajopadhye, 2012]

→ libraries for manipulating unions of LBLs are either absent, limited or no longer maintained

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$$\mathcal{A} = \{Lz + I \mid z \in \mathbb{Z}^d\}$$

- To be in canonical form L and I have to satisfy the condition that the affine homogeneous matrix

$$\hat{L} = \begin{pmatrix} 1 & 0 \cdots 0 \\ I & L \end{pmatrix}$$

is in column left Hermite normal form (HNF)

- the zero columns of \hat{L} are on its right
- ensures uniqueness of the (left) non zero columns of \hat{L}

Example

#offset

#	v1	v2	v3									
1	0	0	0		1	0	0	0	1	0	0	0
2	2	18	20	=	0	2	0	0	1	1	9	10
2	5	60	65		12	5	15	0	-1	0	1	1
2	1	2	3		-6	1	-7	0	0	0	0	1

M

=

H

U

LBL:

$$\mathcal{Z} = \{Lz + l \mid z \in \mathcal{C}, z \in \mathbb{Z}^d\}$$

with a rational coordinate polyhedron:

$$\mathcal{C} = \{z \in \mathbb{Q}^d \mid Cz + c \geq 0\}$$

In normalized form:

- ① canonical lattice function
- ② no equalities in the rational coordinate polyhedron
(but the integer set of points may contain implicit equalities)
- ③ the zero columns of L are eliminated if the sufficient condition that the dark shadow of the coordinate polyhedron covers its exact shadow is verified

Properties:

- if matrix L has no zero columns (on the right) then the LBL is a \mathbf{Z} -polyhedron
- non-uniqueness

Computing the Normalized Form of an LBL

- ① Canonicalize the lattice function
 - compute $L = HU$
 - H is the new lattice function
 - the new coordinate polyhedron is its preimage by U .
- ② Eliminate the equalities of the coordinate polyhedron
(and reduce the dimension of L)
 - compute the integer kernel of the equalities matrix: $K = \text{HNF}(\ker(Eq))$
 - the new lattice function is: LK
 - the new coordinate polyhedron is its preimage by K
- ③ Eliminate zero columns of L
For each zero columns of L :
 - compute the dark shadow and the exact shadow
 - if the exact shadow is contained in the dark shadow remove the column from L and project the (rational) coordinate polyhedron along the corresponding dimension

Normalized Form of Unions of LBLs

A union of LBLs is a list of pairs:

$$(L, D)$$

where L is a PolyLib matrix (in homogeneous form) and D a PolyLib domain.

The normalized form of a union of LBLs is defined as:

- each lattice matrix L of the list is in affine HNF
- it appears at most once in the list
(coordinate polyhedra are merged into polyhedral domains)
- there are no empty coordinate polyhedra in the list
(unless the whole union is a single empty LBL)

Note: non-uniqueness because different lattice decomposition can represent the same set

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```
void AffineHermite(Matrix *A, Matrix **H, Matrix **U)
```

→ compute the affine left HNF of homogeneous matrix A, such that $\hat{A} = \hat{H}\hat{U}$

constant moved as first column (constant dimension)

and homogeneous dimension moved as first row

$$\hat{A} = \begin{pmatrix} 1 & 0 \cdots 0 \\ a & A \end{pmatrix}$$

Algorithm:

- basic HNF engine of PolyLib (similar to Gaussian elimination)

Lattice Intersection

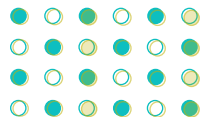
```
Matrix *LatticeIntersection(Matrix *A, Matrix *B)
```

→ compute the intersection of A and B

Algorithm:

① build:

$$T = \left(\begin{array}{cc|cc} 1 & 0\dots 0 & 1 & 0\dots 0 \\ a & A & b & B \\ \hline 1 & 0\dots 0 & 0 & 0\dots 0 \\ a & A & 0 & 0\dots 0 \end{array} \right)$$



② compute H the left HNF of T

③ the bottom right matrix of H is the intersection of the two lattices (zero columns above)

Lattice Complement / Difference

```
LatticeUnion *LatticeDifference(Matrix *A, Matrix *B)
```

- compute the difference ($A \setminus B$)
- A and B must be of exact same dimensions (else the difference might not be finite)
- the result is a **union** of lattices
- if A is NULL, compute the B^c

Algorithm:

- first compute the intersection $J = A \cap B$
- take J out of A: build the matrix spreading all points of A that are not part of J, by scanning the pivots of A and generating alternative rows not intersecting J.



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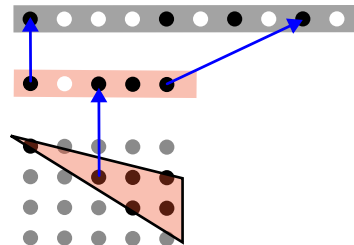
Single LBL image

```
LBL *sLBLImage(LBL *A, Matrix *M)
```

→ compute the image of A by matrix M

Algorithm:

- let $A = (L, D)$
- return the normalized single LBL defined by $(M \cdot L, D)$



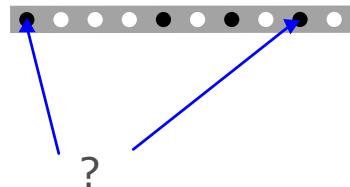
Single LBL preimage

```
LBL *sLBLPreimage(LBL *A, Matrix *M)
```

→ compute the preimage of A by matrix M

Algorithm:

- if M is integer invertible: return the LBL image by M^{-1} of A
- else: compute the LBL as the points z' that verify $Mz' + m = Lz + l$, with $z \in D$ and $A = (L, D)$ and normalize the result to remove the equalities.



Single LBL Intersection

```
LBL *sLBLIntersection(LBL *A, LBL *B)
```

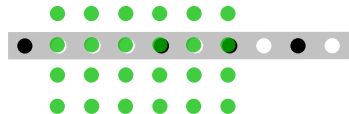
→ compute the intersection $A \cap B$

Algorithm:

- if A and B are Z-domains (their lattices contain no zero column):
return $\text{LBL}(L_A \cap L_B, \text{preimage of } \text{hull}(A) \cap \text{hull}(B))$
- else:
explicitly compute the LBL spread by lattice L_A of the set of points z verifying

$$L_A z + I_A = L_B z' + I_B, \quad z \in D_A, \quad z' \in D_B$$

and normalize the result.



Single LBL Complement

```
LBL *sLBLComplement(LBL *A)
```

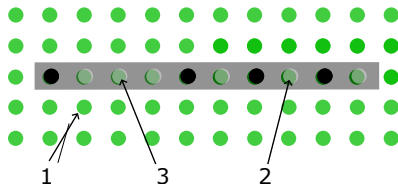
→ compute the complement of A: $A^c = \mathbb{Z}^d \setminus A$

→ used to compute the difference:

$$A \setminus B = A \cap B^c$$

Algorithm: return the union of

- 1 $\text{LBL}(\mathbb{Z}^d, \text{DomainComplement}(\text{hull}(A)))$
- 2 $\text{LBL}(L_A^c, \text{Universe}(\text{dim}))$
- 3 $\text{LBL}(\mathbb{Z}^d, \text{holes}(A))$



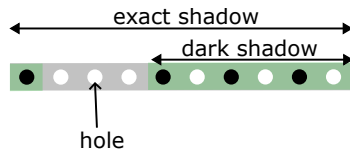
Single LBL to **Z**-Domain

```
LBL *sLBL2ZDomain(LBL *A)
```

- Compute the union of **Z**-polyhedra that is equal to the LBL A .
- If the lattice function of A has some zero columns, they will be removed and the coordinate polyhedron will be split into a union of polyhedra.

Algorithm:

- compute the exact shadow E and the dark shadow D of A
- compute the holes in $E - D$
- implies scanning all points of the coordinate polyhedron that can potentially be holes, check for integer solution
- return $\text{LBL}(L_\emptyset, E - \text{holes})$



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Unions of LBLs: User Exposed Functions

```
LBL *LBLAlloc      (Matrix *Lat, Polyhedron *Domain)
void LBLFree       (LBL *A)
void LBLPrint      (FILE *fp, char *format, LBL *A)
LBL *LBLCopy       (LBL *A)
LBL *EmptyLBL      (int dimension)
LBL *UniverseLBL   (int dimension)
Bool isEmptyLBL    (LBL *A)

void LBLCanonical   (LBL *A)
LBL *LBLUnion       (LBL *A, LBL *B)
LBL *LBLImage       (LBL *A, Matrix *M)
LBL *LBLPreimage    (LBL *A, Matrix *M)
LBL *LBLIntersection (LBL *A, LBL *B)
LBL *LBLDifference   (LBL *A, LBL *B)
void LBLSimplifyEmpty(LBL *A)           // remove integer-empty polyhedra
Bool LBLIncluded     (LBL *A, LBL *B)    // if simple checks fail,
                                         // check emptiness of the difference
LBL *LBL2ZDomain     (LBL *A)
```

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- fast, robust, unified library implementation for manipulating **Z**-polyhedra, LBLs, and their union.
- Try it: <https://github.com/vincentloechner/polylib/tree/LBL>
- ongoing work: provide functions to facilitate enumeration and scanning

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